

***Crashworthiness of Composite Structures: Modeling of the
Crushing of UD Tape Sinusoidal Specimens using a Progressive
Failure Model***

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Introduction

- *Importance of crashworthiness over “the stronger, the better” philosophy*
- *Controlled collapse ensuring safe dissipation of kinetic energy and limiting the seriousness of injuries incurred by the occupants*
- *Fiber-reinforced plastics (FRPs) can be designed to provide normalized energy absorption capabilities which are superior to those of metals*
- *Understanding prediction of the energy absorption of FRPs is not a straightforward matter*
- *FRPs are bi-phasic by nature and inherently anisotropic, their mechanical behavior is determined by a complex interpolation of a large number of variables*
- *The brittle nature of most fibers and thermosets tends to generate a brittle mode of failure*

Compressive Failure Mechanism: Brittle Fracture

- *Euler buckling, progressive folding, progressive crushing*
- *CFRPs typically fail by progressive crushing. Very high levels of specific energy absorption.*
- *Splaying and fragmentation failure modes*
- *The behavior of composite materials under crash conditions poses particular challenges: modeling beyond the elastic region and into failure initiation and propagation*
- *The crushing behavior of FRPs results in the interaction of failure mechanisms: matrix cracking and splitting, delamination, fiber tensile fracture and compressive kinking, frond formation and bending, and friction*
- *Current analysis methods are not capable of capturing physical behavior at the micro-level (fiber, matrix, interface) and different failure mechanisms*



Sensitivity of the model

- *Lamina-level failure criteria have been used, although with well-accepted limitations, to predict the onset of damage within laminated codes. A degradation scheme is used to reduce the material properties once failure initiated*
- *With today's computational power it is not possible to capture each of the failure mechanisms. Explicit finite element code: solves equations of motion numerically by direct integration using explicit methods*
- *Commercially available non-linear finite element packages, e.g. LS-DYNA, PAMCRASH, ABAQUS EXPLICIT, RADIOSS, are the most viable way of analyzing the crashworthiness of composite structures*
- *Commercial FEA codes use material models (or MAT cards): Progressive failure (PFM) and continuum damage mechanics (CDM) material models*
- *Each material model utilizes a different modeling strategy: failure criterion, degradation scheme, mat props, and set of parameters that are needed for computation but do not have an immediate physical meaning*
- *MAT54 is a progressive failure material model*

LS-DYNA MAT54



- The material cards comprise material properties based on coupon-level test data
 - Elastic and failure (strengths, strains)
- Everything else is a mix of mathematical expedients, correction factors that either cannot be measured by experiment or have no direct physical meaning - these need to be calibrated by trial and error

***MAT_054 (ENHANCED_COMPOSITE_DAMAGE)**

| | | | | | | | |
|----------|----------|----------|----------|----------|-------|--------|--------|
| mid | ro | ea | eb | (ec) | prba | (prca) | (prcb) |
| 1 | 1.50E-04 | 8.11E+06 | 7.89E+06 | 1.00E+00 | 0.043 | 0 | 0 |
| gab | gbc | gca | (kt) | aopt | | | |
| 6.09E+05 | 6.09E+05 | 6.09E+05 | 0 | 3 | | | |
| xp | yp | zp | a1 | a2 | a3 | mangle | |
| 0 | 0 | 0 | 0 | 0 | 0 | 90 | |
| v1 | v2 | v3 | d1 | d2 | d3 | dfailm | dfails |
| 0 | 0 | 1 | 0 | 0 | 0 | 0.013 | 0.03 |
| tfail | alph | soft | fbrt | ycfac | dfait | dfailc | ets |
| 1.00E-09 | 0.3 | 0.5 | 0.95 | 1.2 | 0.02 | -0.013 | 0 |
| xc | xt | yc | yt | sc | crit | beta | |
| 1.03E+05 | 1.32E+05 | 1.40E+05 | 1.12E+05 | 1.90E+04 | 54 | 0.5 | |

Material properties:
elastic

Material properties:
strength and strain to failure

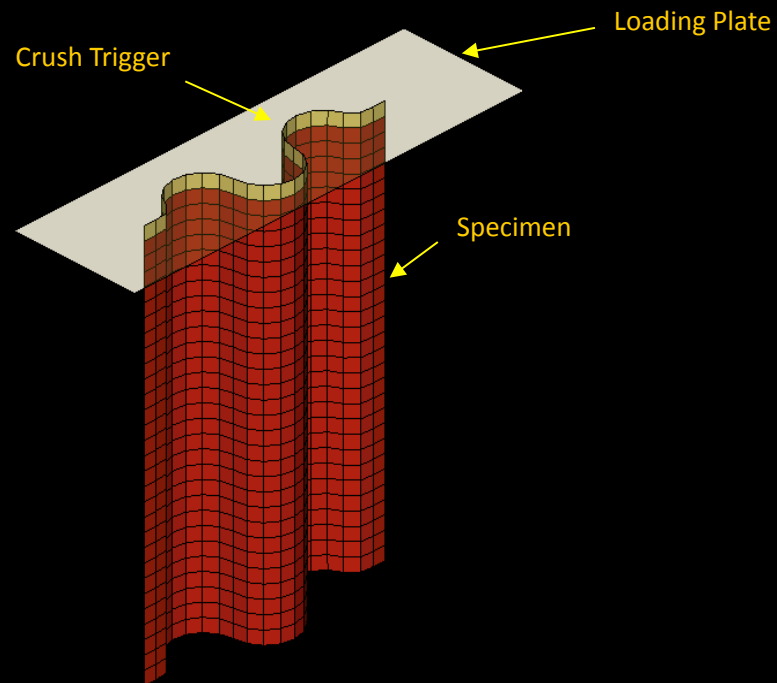
Material Model: MAT 54



- *Model is very sensitive to:*
 - *Filtering*
 - *Mesh size*
 - *Test speed*
 - *Contact definition*
 - *Contact type*
 - *LP curve*
 - *Trigger characteristics*
 - *Material model*

| Parameter | Baseline Value | Parametric Variation | Figure |
|--------------------------------|--------------------|--|--------|
| MAT54: XT | 319000 | 0, 5000, 50000, 150000, 250000, 300000, 350000, 370000, 400000, 500000, 640000 | - |
| MAT54: XC | -213000 | 0, -100000, -150000, -200000, -230000, -250000, -265000, -275000, -300000 | 8 |
| MAT54: SC | 22400 | 1, 10000, 15000, 175000, 18000, 19000, 20000, 30000, 35000, 50000 | 9 |
| MAT54: YT | 7090 | 0, 3000, 6800, 7500, 10000, 50000, 500000 | - |
| MAT54: YC | -28800 | 0, -5000, -15000, -25000, -30000, -35000, -70000, -200000, -288000, -320000, -400000, -500000 | - |
| MAT54: DFAILT | 0.0174 | 0, 0.005, 0.00625, 0.00688, 0.0075, 0.01, 0.015, 0.04, 0.08 | 10 |
| MAT54: DFAILC | -0.0116 | 0, -0.005, -0.0075, -0.00813, -0.00875, -0.01, -0.012, -0.015, -0.02, -0.0225, -0.025, -0.03, -0.1 | 11 |
| MAT54: DFAILM | 0.024 | 0, 0.01, 0.015, 0.0163, 0.0165, 0.018, 0.02, 0.03, 0.06 | 12 |
| MAT54: DFAILS | 0.03 | 0, 0.006, 0.01, 0.037, 0.05, 0.1 | - |
| MAT54: EFS | 0 | 0.01, 0.5, 1 | - |
| MAT54: ALPH | 0.3 | 0, 1.00E-14, 1.00E-6, 1.00E-4, 1.00E-3, 0.03, 0.9, 1 | - |
| MAT54: BETA | 0.5 | 0, 1 | - |
| MAT54: FBRT | 0.5 | 0, 0.1, 0.95, 1 | - |
| MAT54: YCFAC | 1.2 | 0, 0.5, 2, 4, 7.396, 9 | - |
| MAT54: TFAIL | 0.115E-08 | 0, 1E-07, 0.05, 0.11 | - |
| MAT54: SOFT | 0.57 | -0.5, 0, 0.05, 0.4, 0.55, 0.565, 0.575, 0.6, 0.8, 2 | 13 |
| SAE Filter frequency | 600 | 180, 1000 | 14 |
| Crush Speed | 150 | 1.5, 15, 50 | 15 |
| Contact Load-Penetration Curve | PCWL | PCWL Stiff, PCWL Soft, Linear | 16-19 |
| Mesh Size | 0.1 | 0.05, 0.15, 0.2 | 20, 21 |
| Trigger Thickness | 0.01 | 0.005, 0.015, 0.020, 0.025, 0.030, 0.035, 0.040, 0.045, 0.047, 0.050, 0.060, 0.079 | 22 |
| Trigger Geometry | Constant thickness | Tapered thickness | 23 |

Baseline Model

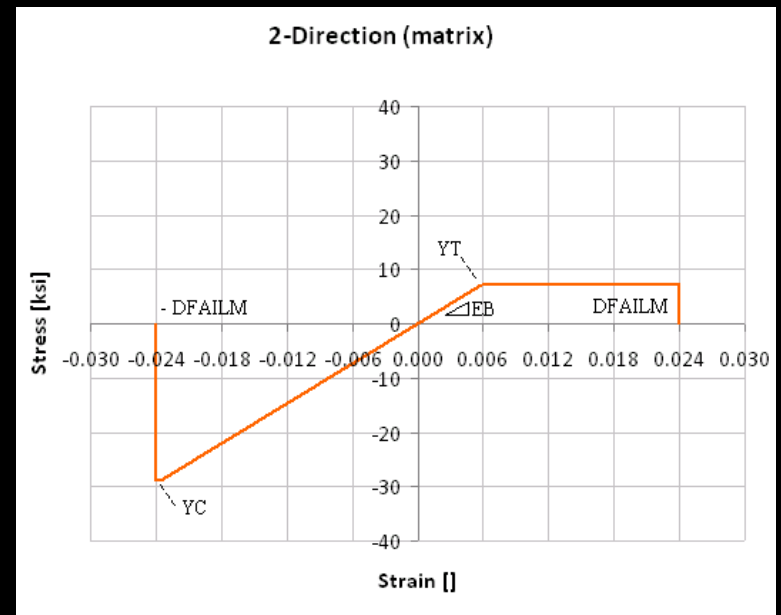
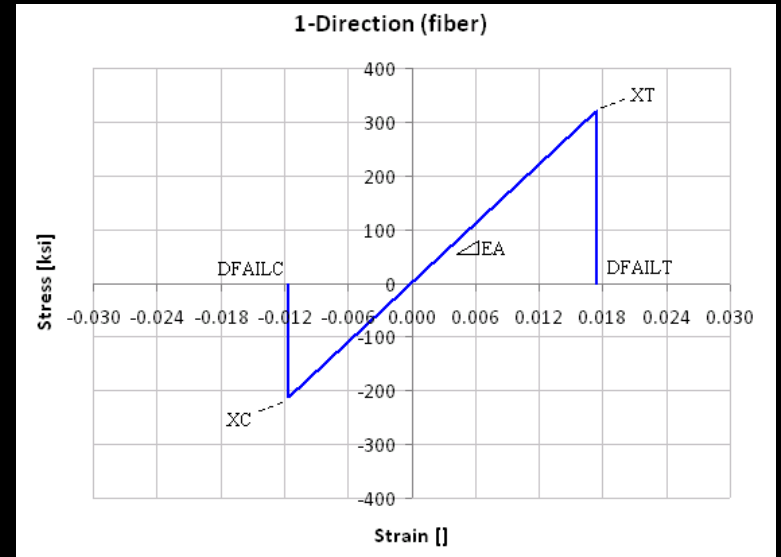


- *Toray AGATE material for General Aviation*
 - *Toray T700 carbon fiber UD tape 12k tow*
 - *2510 epoxy resin, oven cure, 270 F*
- *Lay-up [(0/90)_{3s}], 0.079 in. thick*
- *840 shell elements*
- *SPC Boundary conditions on bottom row of elements*
- *Contact Algorithm: ENTITY*

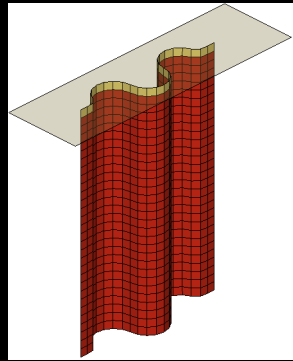
Baseline Model



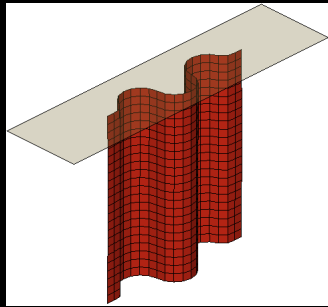
| Property | Symbol | LS-DYNA Parameter | Experimental Value |
|--------------------------------------|---------------|-------------------|--|
| Density | ρ | RO | 0.055 lb/in ³ (1.52 g/cm ³) |
| Modulus in 1-direction | E_1 | EA | 18.4 Msi (127 GPa) |
| Modulus in 2-direction | E_2 | EB | 1.22 Msi (8.41 GPa) |
| Shear Modulus | G_{12} | GAB | 0.61 Msi (4.21 GPa) |
| Major Poisson's ratio | ν_{12} | - | 0.309 |
| Minor Poisson's ratio | ν_{21} | PRBA | 0.02049 |
| Strength in 1-direction, tension | F_1^{tu} | XT | 319 ksi (2.20 GPa) |
| Strength in 2-direction, tension | F_2^{tu} | YT | 7.09 ksi (48.9 MPa) |
| Strength in 1-direction, compression | F_1^{cu} | XC | 213 ksi (1.47 GPa) |
| Strength in 2-direction, compression | F_2^{cu} | YC | 28.8 ksi (199 MPa) |
| Shear Strength | F_{12}^{su} | SC | 22.4 ksi (154 MPa) |



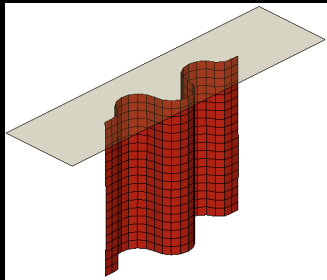
Baseline Model



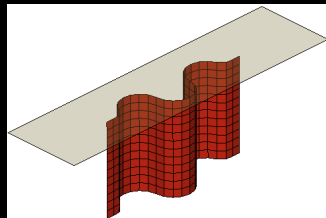
t = 0.00 s



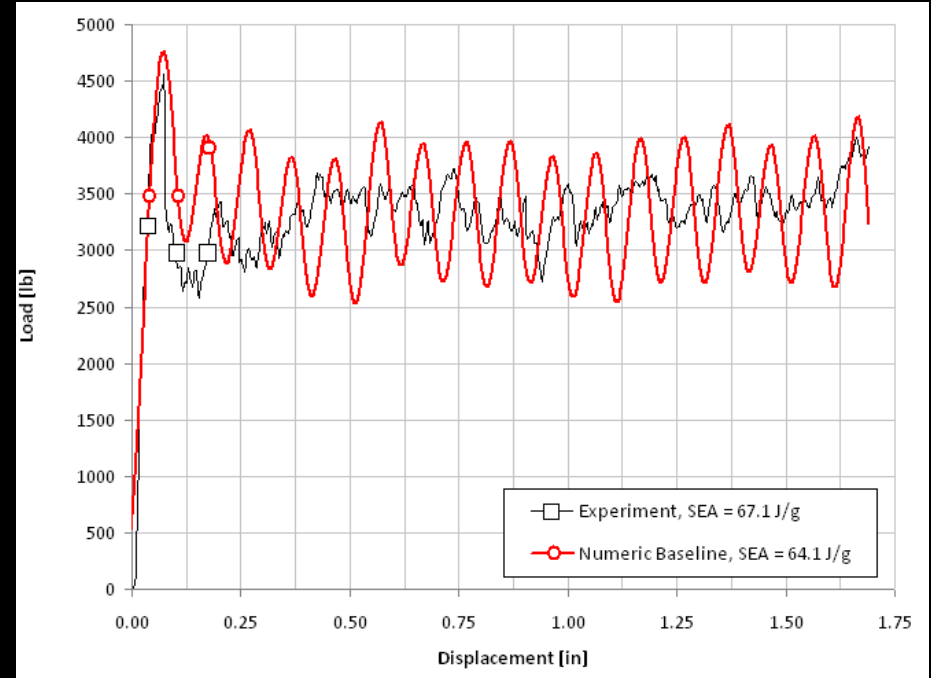
t = 0.004543 s



t = 0.006873 s

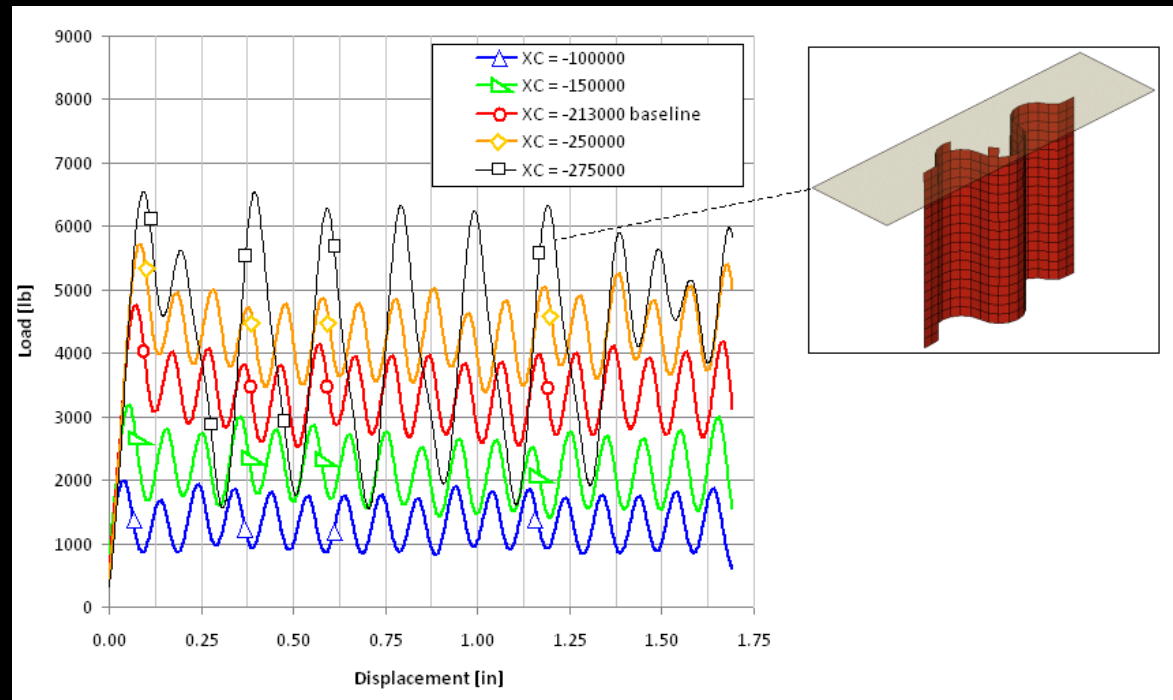


t = 0.01153 s



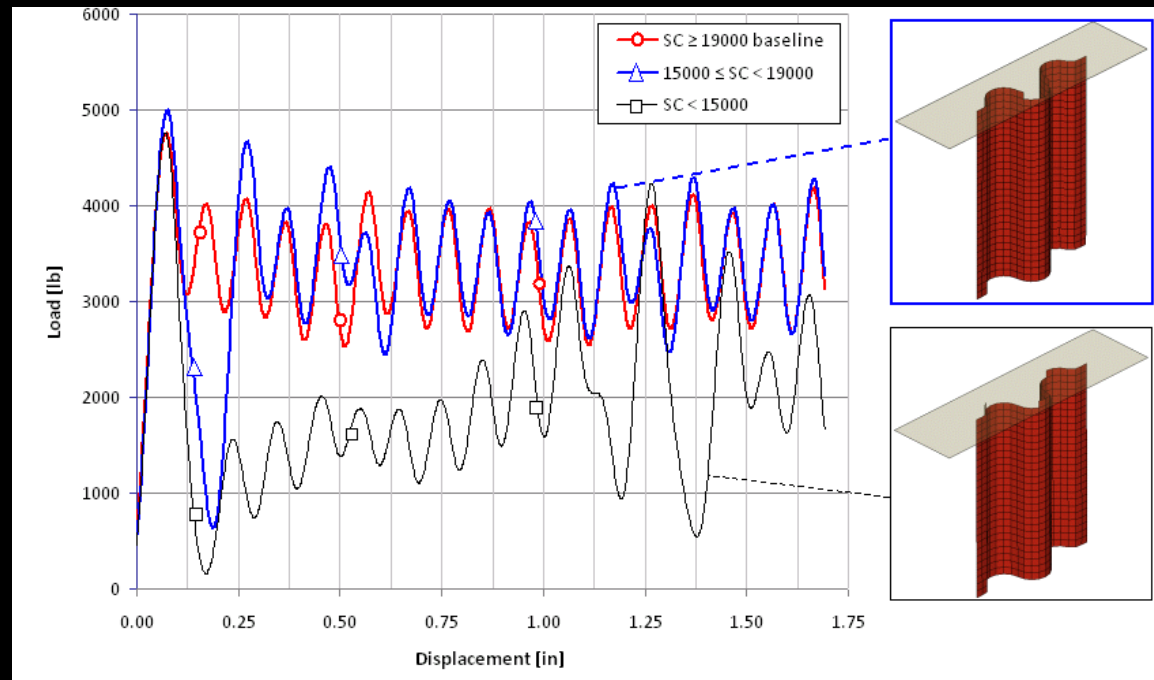
- *Obtained by inputting material properties and adjusting the control parameters, e.g SOFT, FBRT, YCFAC, and model specifics: mesh size, LP curve*
- *Failure advances in an even and stable fashion, through element deletion at the crush front*

Compressive Strength: X_c



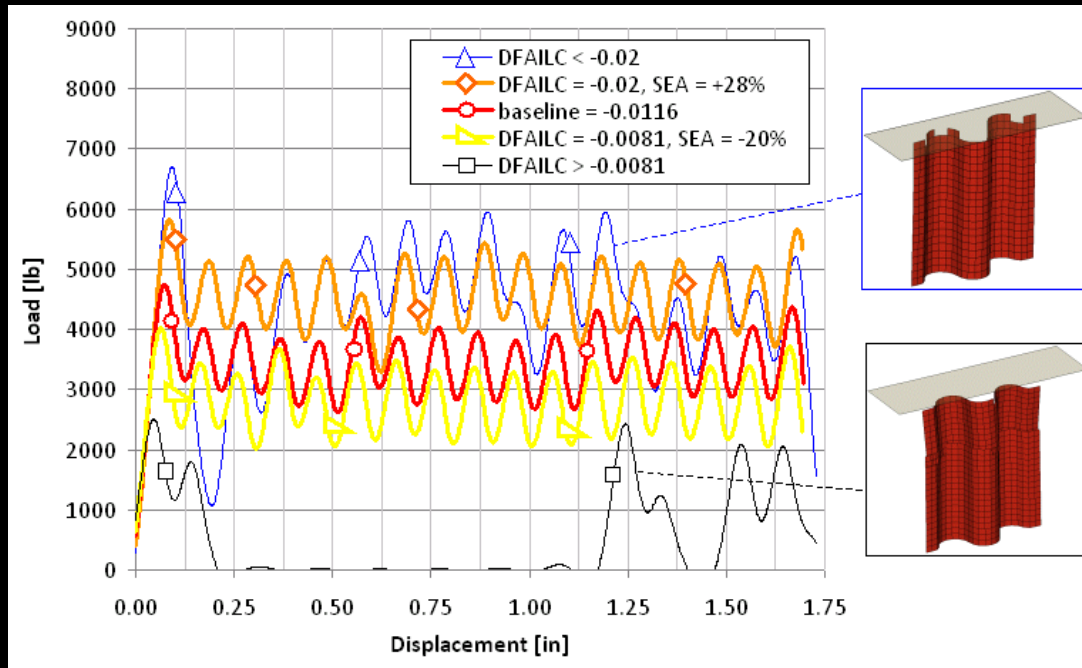
- *An effective model needs to be sufficiently robust to tolerate variations in material property input data, in order to accommodate statistical variation in measured strength and stiffness data, and yet sensitive enough to capture more significant variations*
- *Small increments in X_c (Abs val) significantly lower the avg crush load and vice-versa*
- *Instability over 275 ksi compressive strength*

Shear Strength: Sc



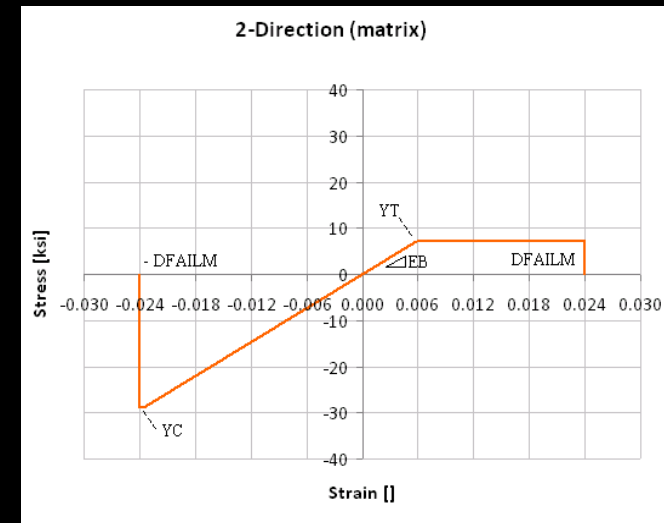
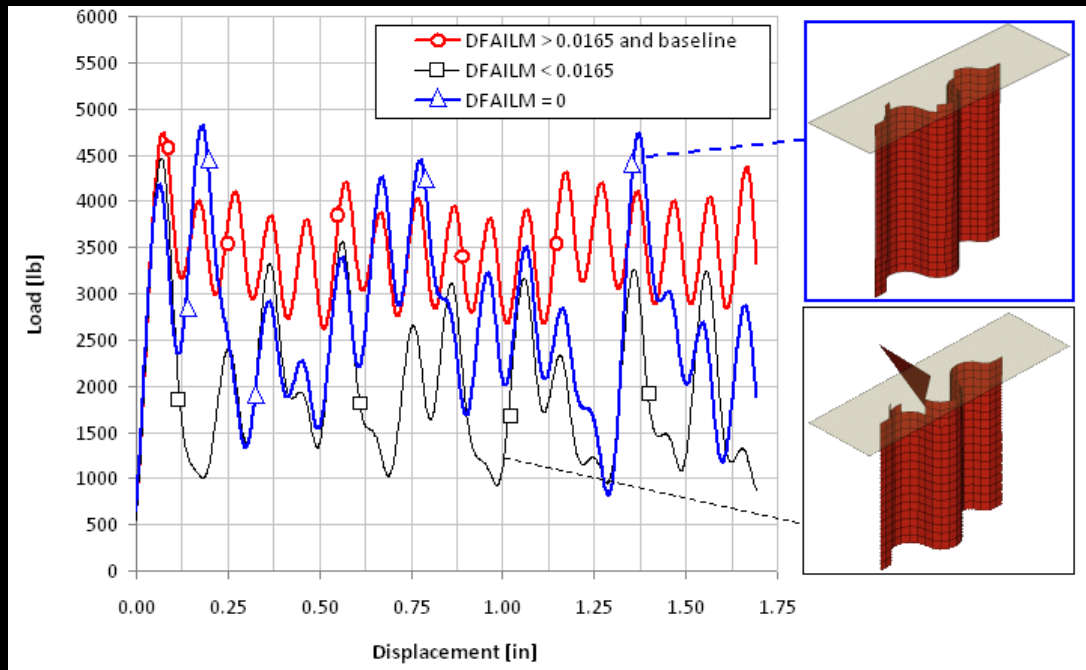
- *Unexpected and peculiar influence on stability*
- *Increasing SC does not affect the results.*
- *Decreasing SC by even 15% creates significant instabilities*
- *MAT 54 does not have a failure criterion dedicated to shear strength but SC appears to be interactive in the tensile fiber, tensile matrix, compressive matrix failure modes*
- *15% is within experimental error for shear*

Compressive Fiber Failure Strain: DFAILC



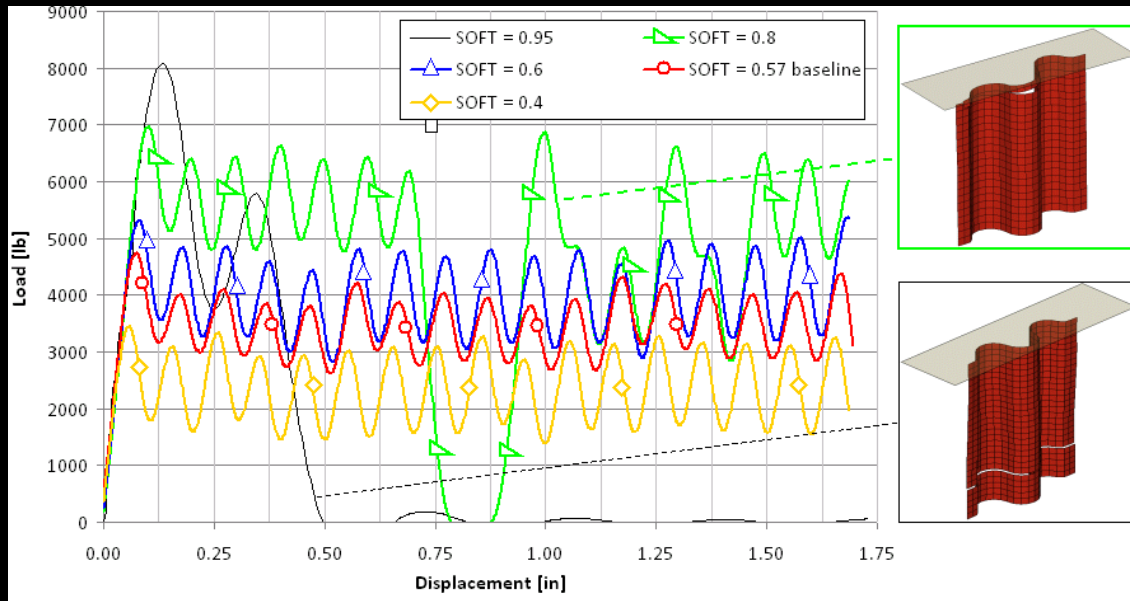
- *The compressive strain to failure has a deep effect on numerical results*
- *DFAILC = -0.02 (72% increase) results in a 28% increase in SEA, model is stable*
- *DFAILC = -0.0081 (70% decrease) results in a 20% decrease in SEA, model is stable,*
- *Higher divergences from baseline DFAILC results in numerical instabilities*

Matrix Failure Strain: DFAILM



- Zone of virtual plasticity for matrix tension
- BL DFAILM = 0.024
- Increasing DFAILM, therefore increasing perfectly plastic zone does not affect results
- DFAILM below 0.0165 results in model instabilities (45% change)

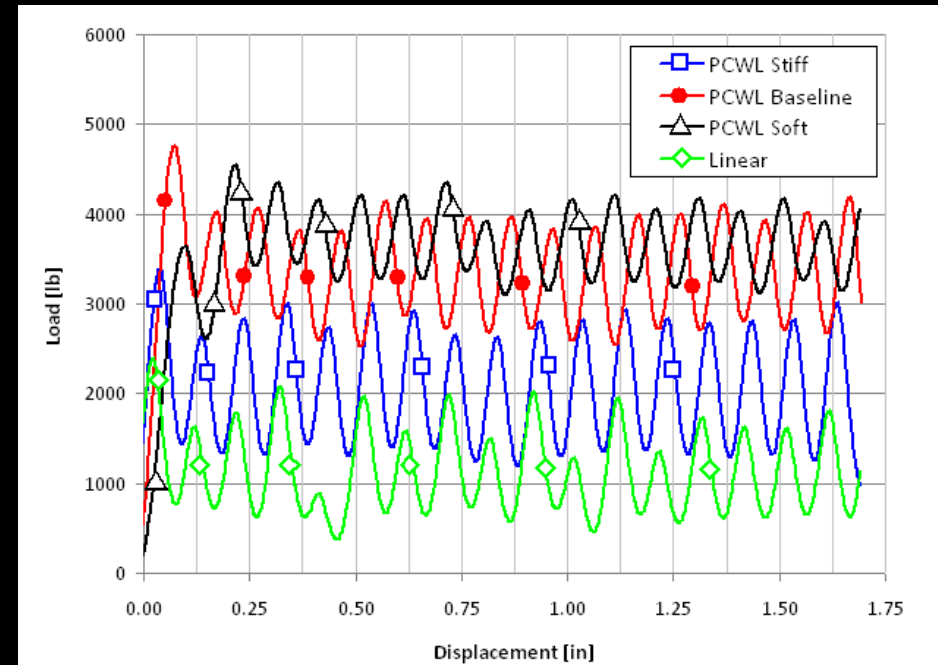
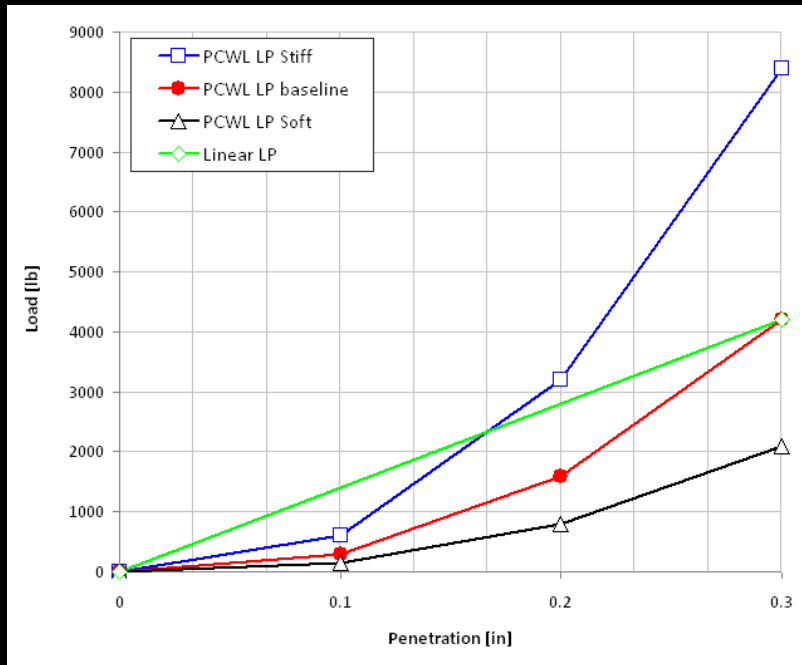
Reduction Factor: SOFT



| SOFT | SEA [J/g] |
|-------------|--------------------|
| 0.05 | 2.74 |
| 0.4 | 48.8 |
| 0.57 | 64.12 |
| 0.6 | 75.8 |
| 0.8 | 87.1 |
| 0.95 | immediate buckling |

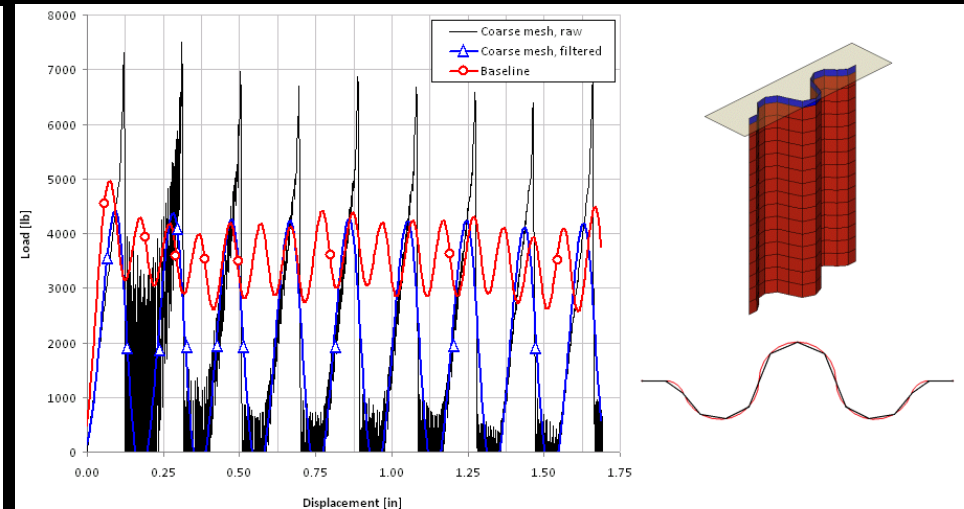
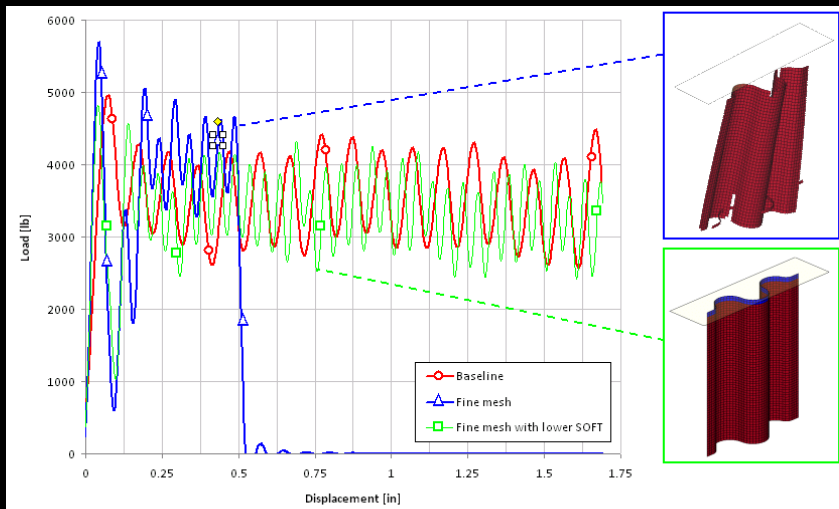
- *SOFT artificially reduces the strength of the row of elements immediately ahead of the active crush front*
- *Mathematical expedient to avoid global buckling*
- *Physical interpretation: damage zone (delaminations and cracks) ahead of crush front*
- *It is the single most influential parameter in the input deck*
- *Capable of dictating whether a simulation is stable or unstable*

Contact Load Penetration Curve



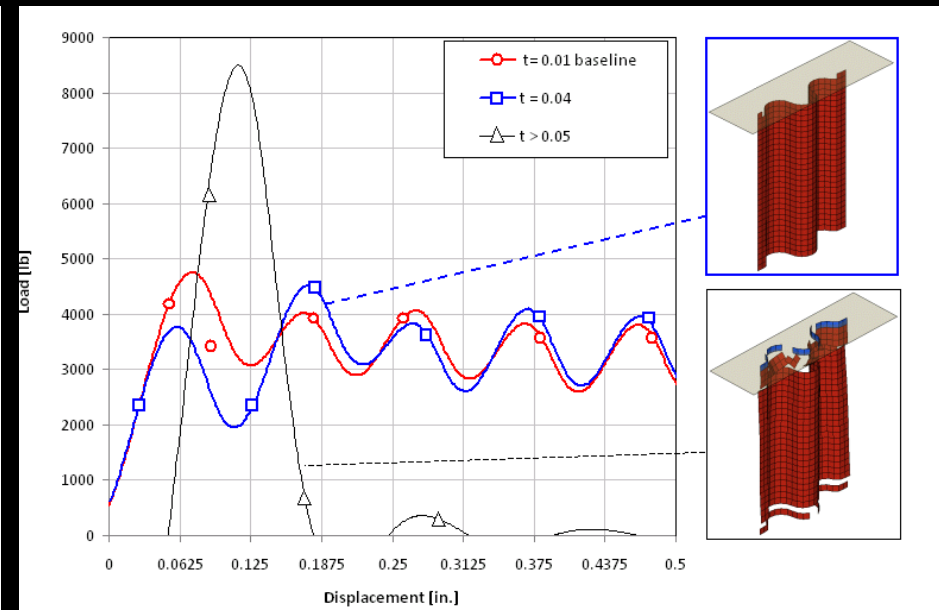
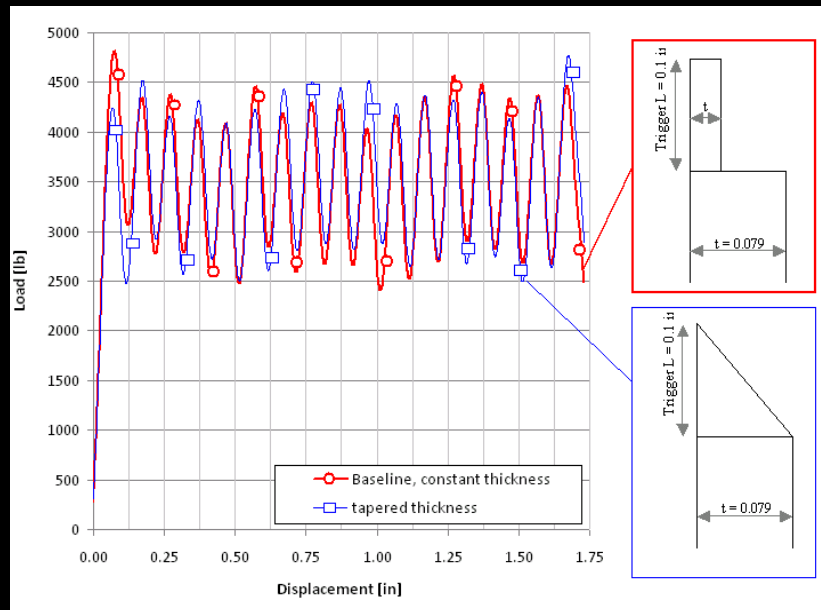
- *The LP curve has a deep effect on the numerical results*
- *There is no way of knowing a priori or determining experimentally what correct shape needs to have for specific material / geometry / loading combination*
- *Trial and error*
- *PCWL adopted for baseline*
- *Stiff LP curve: introduces load more suddenly. Soft LP curve: introduces load more gradually*

Mesh Size



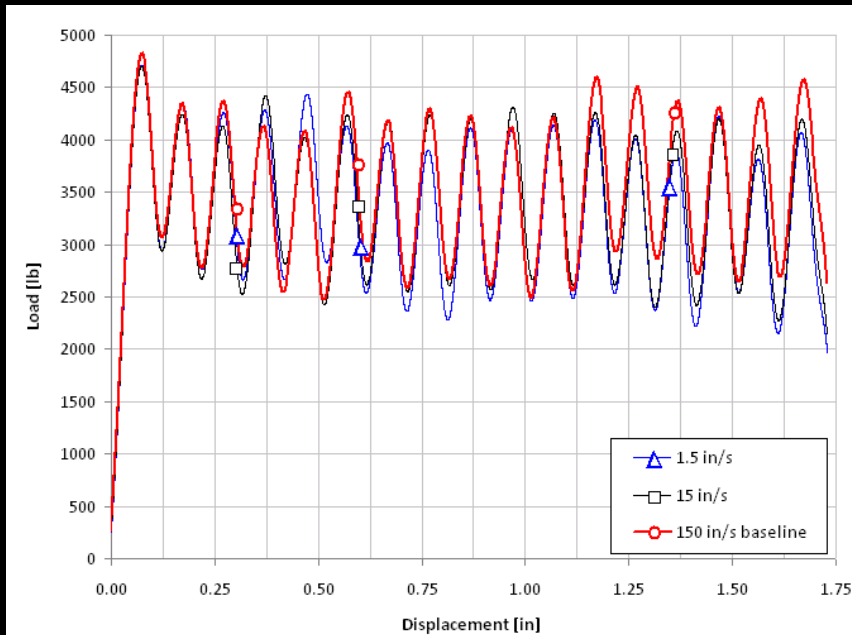
- *Coarse mesh: 0.2 in. Runtime: 43 sec. Mesh is too coarse, dead time between rows. Softening LP curve and increasing SOFT value is not sufficient to fix problem*
- *Baseline mesh: 0.1 in. Runtime: 96 sec*
- *Fine mesh: 0.05 in. Runtime: 7 min and 19 sec. With BL parameters it results in buckling. Reducing SOFT to 0.5 fixes overall stability. LP curve not able to fix initial instability*

Trigger Thickness and Geometry



- *Crush trigger responsible for initial behavior of crushing: initial peak load and crush stability*
- *Baseline trigger: row of reduced thickness*
- *Greater thickness results in lower initial load because of filtering apparent phenomenon*
- *$t > 0.05$ in. results in global buckling*
- *Trigger thickness dependent of contact algorithm*
- *Tapered trigger resembles real physical trigger and has very similar global response and average crush*

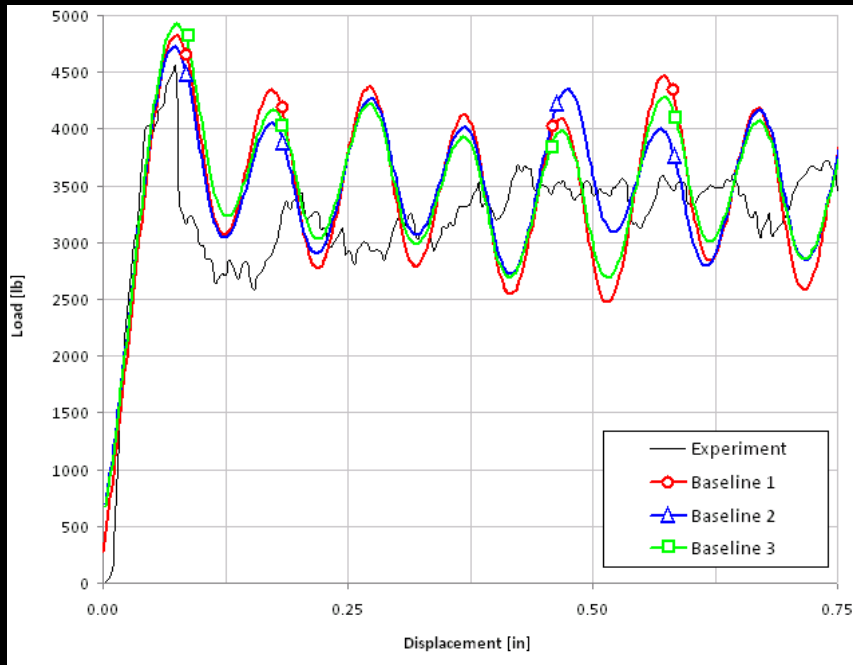
Loading Speed



| Loading rate [in/s] | Runtime [min] |
|---------------------|---------------|
| 1.5 | 164 |
| 15 | 16 |
| 150 | 1.6 |

- *True experimental crush loading rate is: 1.0 [in/min]*
- *To reduce experimental cost, simulations are performed at: 150 [in/s]*
- *No strain-rate dependent material properties in material card, no possible strain-rate dependent behavior*
- *Inertial effects might arise*

Multiple Baselines



- Varying the material properties within the experimental CoV gives rise to many different combinations of SOFT, DFAILC and XC that give excellent agreement with the experimental evidence

| Baseline | Contact Type | LP Curve | Mesh size | SOFT | DFAILC | XC | SEA [J/g] | % Error |
|----------|--------------|---------------|-----------|-------|---------|----------|-----------|---------|
| 1 | Entity | PCWL baseline | 0.1 | 0.57 | -0.0116 | -213,000 | 64.12 | -4.4 % |
| 2 | | | | 0.48 | -0.0175 | -213,000 | 67.32 | +0.4 % |
| 3 | | | | 0.615 | -0.0100 | -213,000 | 67.80 | +1.1 % |
| 4 | | | | 0.62 | -0.0116 | -200,000 | 66.39 | -1.0% |
| 5 | | | | 0.54 | -0.0116 | -230,000 | 66.49 | -0.9% |

Conclusions

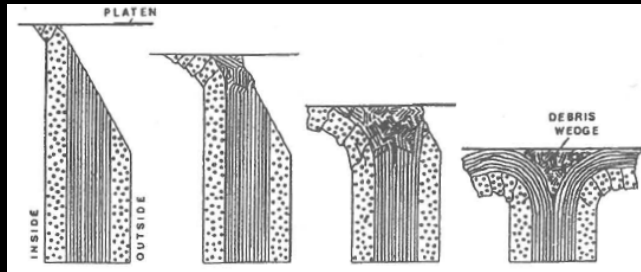
- *Current modeling approach with LS-DYNA MAT54 is not predictive at this structural level (element)*
- *The simulation can be matched to the experiment but cannot predict it*
- *Through proper calibration at the coupon and element level, it is possible however to use the model to predict the behavior of higher structural levels (subcomponent and full-scale)*
- *The parameters: XC, SC, DFAILC, DFAILM were found to have a significant effect on the numerical results*
- *SOFT and contact definition (LP curve in particular) gave dramatic effects on results of simulations. Yet they cannot be determined a priori but only calibrated to match experiment*
- *Varying the loading speed was found to not have a significant effect on the numerical results*

References

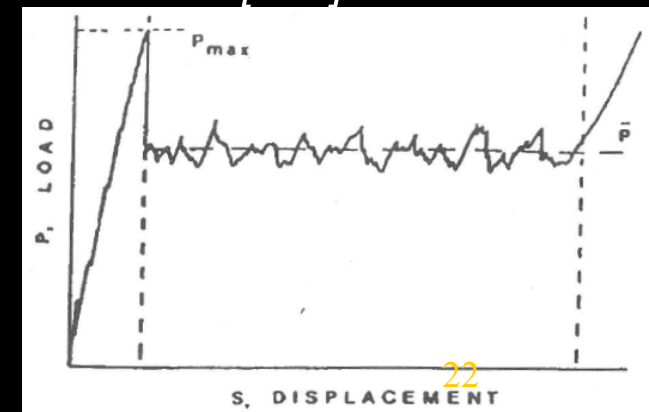
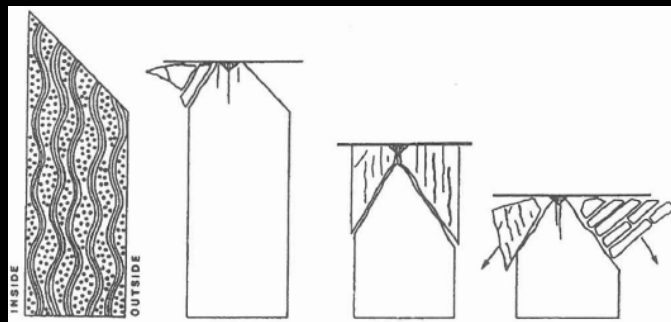
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APPENDIX: Brittle Fracture

- *Progressive Crushing: CFRPs and GFRPs typically fail by this mechanisms. Very high levels of energy absorption. Serrations: stresses required to initiate crack growth are higher than those for propagation.*
- *Splaying crushing mode: very long interlaminar, intralaminar, and parallel to fiber cracks. Little or none fracture of axial lamina bundles. Crack growth is the principal energy absorption mechanism [Hull].*



- *Fragmentation crushing mode: wedge-shaped laminate cross section. Short interlaminar and longitudinal cracks forming partial lamina bundles. Fracture of the lamina bundles is the primary energy absorption mechanism [Hull].*



Appendix: MAT 54 Failure Criteria

- For the tensile fiber mode where $\sigma_{11} > 0$:

$$e_f^2 = \left(\frac{\sigma_{11}}{F_{1t}}\right)^2 + \beta \left(\frac{\sigma_{12}}{F_{12s}}\right)^2 \begin{cases} \geq 1 & \text{failed} \\ < 1 & \text{elastic} \end{cases}$$

Upon failure: $E1 = E2 = G12 = \nu_{12} = \nu_{21} = 0$

For $BETA = 1$ the Hashin failure criterion is implemented, while setting $BETA = 0$ reduces to the Maximum Stress failure criterion.

- For the compressive fiber mode where $\sigma_{11} < 0$:

$$e_c^2 = \left(\frac{\sigma_{11}}{F_{1c}}\right)^2 \begin{cases} \geq 1 & \text{failed} \\ < 1 & \text{elastic} \end{cases}$$

Upon failure: $E1 = \nu_{12} = \nu_{21} = 0$

- For the tensile matrix mode where $\sigma_{22} > 0$:

$$e_m^2 = \left(\frac{\sigma_{22}}{F_{2t}}\right)^2 + \left(\frac{\sigma_{12}}{F_{12s}}\right)^2 \begin{cases} \geq 1 & \text{failed} \\ < 1 & \text{elastic} \end{cases}$$

Upon failure: $E2 = \nu_{21} = G12 = 0$

- For the compressive matrix mode where $\sigma_{22} < 0$:

$$e_d^2 = \left(\frac{\sigma_{22}}{2F_{12s}}\right)^2 + \left[\left(\frac{F_{2cu}}{2F_{12s}}\right)^2 - 1\right] \frac{\sigma_{22}}{F_{2cu}} + \left(\frac{\sigma_{12}}{F_{12s}}\right)^2 \begin{cases} \geq 1 & \text{failed} \\ < 1 & \text{elastic} \end{cases}$$

Upon failure: $E2 = \nu_{21} = \nu_{12} = 0 = G12 = 0$

Beside strength-based criteria, failure can also occur if the strains exceed the strain to failure for each ply. Element deletion can also occur if the element time step $TFAIL$ is exceeded.

Appendix: FBRT and YCFAC



- Matrix failure corresponds to first ply failure . The FBRT and YCFAC strength reduction parameters are used to degrade the pristine fiber strengths of the remaining plies once matrix failure takes place

$$X_T = X_T^* * FBRT$$

$$X_C = Y_C^* * YCFAC$$

- The FBRT factor acts as a percentage reduction of the tensile fiber strength from its pristine value, therefore its value may only be in the range [0, 1]. The YCFAC factor uses the pristine matrix strength Y_C to determine the damaged compressive fiber strength [0, 7.4]
- The input value for the two parameters FBRT and YCFAC cannot be measured experimentally and need to be determined by trial and error
- First ply failure is in the tensile matrix mode. The FBRT & YCFAC strength reduction parameters are active after compressive matrix failure
- Results show that the simulation is unaffected by the fiber strength degradation scheme. These factors have negligible effect on the results of the simulation

Appendix: TFAIL

- The simulation runs unaffected for small values of TFAIL, such as [1E-08, 1E-05]
- Using TFAIL = 0 leads to immediate global buckling because of the SOFT condition violation
- Using large TFAIL values in the range [0.001, 0.1] should be avoided, since the time-step of the simulation is smaller and elements are deleted before being loaded
- It should be emphasized that LS-DYNA assigns the time-step automatically to ensure that the Courant condition is satisfied. In this case the default time-step is 2.44219 E-7

- Courant Condition:
$$\Delta t = \frac{k\Delta h}{c}$$

- Where, Δt is the time step, Δh is the characteristic mesh dimension, k is a stability factor (0.6 – 0.8), and c is the speed of the sound wave through the material